

An Initial Investigation into Fixed and Adaptive Stopping Strategies

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Abstract

Most models, measures and simulations often assume that a searcher will stop at a predetermined place in a ranked list of results. Real-world searchers however adapt their interactions with a ranked list based upon their interpretation of it. This poster presents our initial simulated analysis of stopping rules, exploring a fixed depth and two adaptive strategies in the context of ad-hoc topic retrieval.

Stopping Rules and Strategies

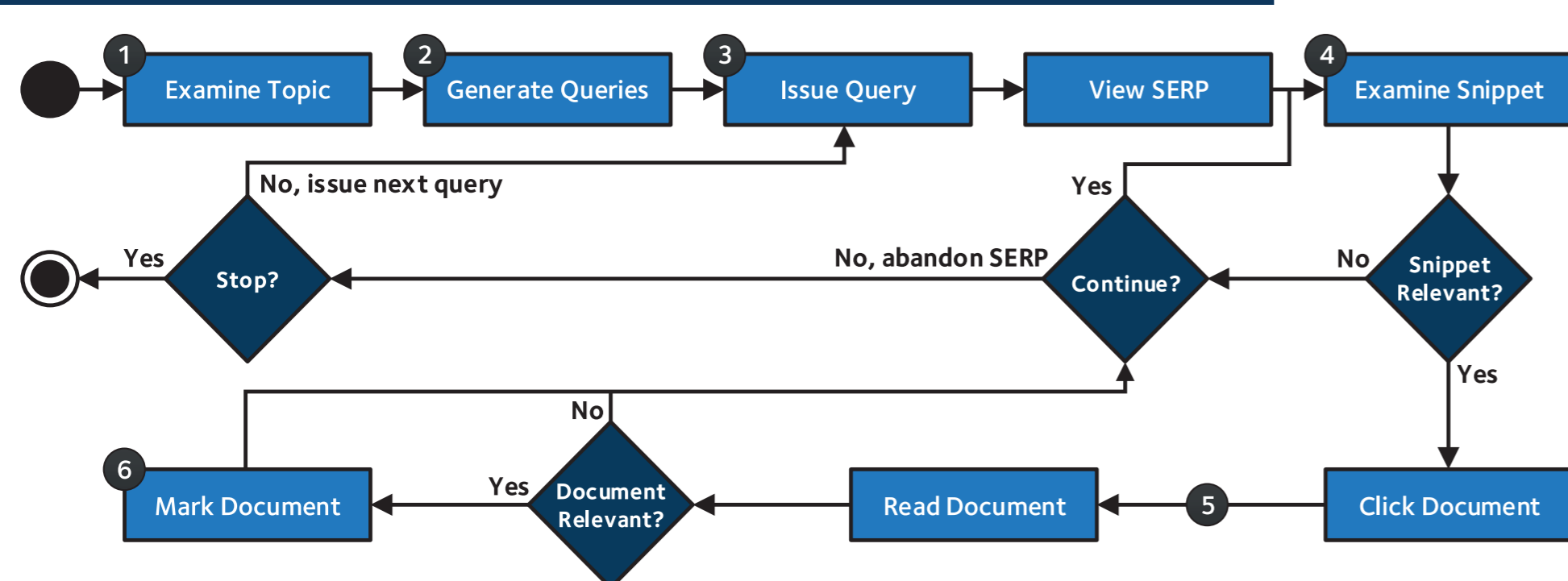
Knowing when to stop is considered a fundamental aspect of human behaviour. Studies have shown that we stop searching when we feel that what we have found is "good enough". Researchers have however devised a series of stopping rules, two of which (*frustration and disgust rules*) we operationalised for this study.

SS1: A fixed depth stopping strategy

SS2: Stop examining the results list after observing a total of x non-relevant snippets

SS3: Stop examining the results list after observing x non-relevant snippets in a row

The Simulator and Method



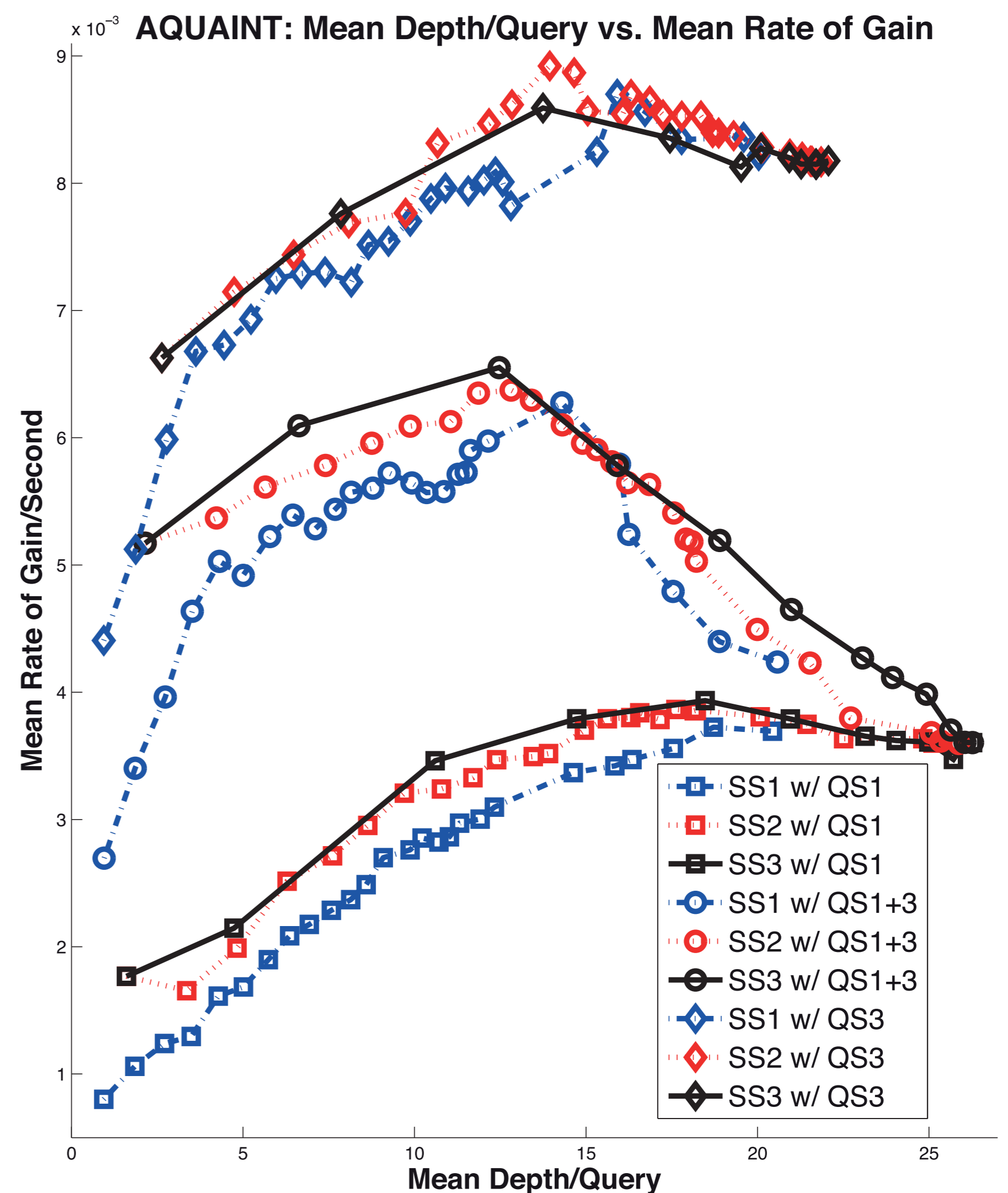
We developed a simulator based upon the user models defined by Baskaya et al. (2013) and Thomas et al. (2014). Simulated searchers examined 50 topics over the AQUAINT and WT2g collections. The goal was to find as many relevant documents in 20 simulated minutes. We also used three querying strategies from Keskustalo et al. (2009).

QS1: Generation of single-term queries (poor performance).

QS3: Generation of tri-term queries (good performance).

QS1+3: A blended strategy of QS1 and QS3, to examine the robustness of the three stopping strategies.

Results



SS1 achieved its highest level of CG with high thresholds (25-50), much deeper than what is typically used in simulations (10 snippets/documents per query)

SS2 also achieves its best performance over a wide range of thresholds

SS3 appeared to be the most consistent of the three stopping strategies, with reasonable thresholds ranging from 3-5 (stop after 3-5 non-relevant snippets in a row)

We deduce that **SS3** appears the most robust.

Similar findings were found over the WT2g collection

Future Work

Explore a greater variety of stopping strategies

Compare stopping strategies to actual stopping behaviour

Examine the relationship between the quality of the results list and interaction probabilities (i.e. how does performance affect interaction?)

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